

**Human detection and following by a mobile robot using 3D features**

Ali, Badar; Iqbal, Khawaja Fahad; Ayaz, Yasar; **Muhammad, Naveed** Proceedings of 2013 IEEE International Conference on Mechatronics and Automation (ICMA) : August 4-7, Takamatsu, Japan 2013 / p. 1714-1719 : ill

**Potential guided directional-RRT\* for accelerated motion planning in cluttered environments**

Qureshi, Ahmed Hussain; Iqbal, Khawaja Fahad; **Muhammad, Naveed** Proceedings of 2013 IEEE International Conference on Mechatronics and Automation (ICMA) : August 4-7, Takamatsu, Japan 2013 / p. 519-524 : ill