

Collective responses of a large mackerel school depend on the size and speed of a robotic fish but not on tail motion
Kruusmaa, Maarja; Rieucan, Guillaume; Castillo Montoya, Jose Carlos; **Markna, Riho**; Handegard, Nils Olav Bioinspiration & biomimetics 2016 / p. 1-12 : ill <https://doi.org/10.1088/1748-3190/11/5/056020> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Design principle of a biomimetic underwater robot U-CAT

Salumäe, Taavi; Raag, Rasmus; Rebane, Jaan; Ernits, Andres; Toming, Gert; Ratas, Mart; **Kruusmaa, Maarja** OCEANS'14 MTS/IEEE St. John's : St. Johns, Newfoundland, Canada, 14-19 September 2014 2014 / [5] p. : ill

Fault-tolerant control allocation for a bio-inspired underactuated AUV in the presence of actuator failures : design and experiments

Remmas, Mohamed Walid; Chemori, Ahmed; **Kruusmaa, Maarja** Ocean engineering 2023 / art. 115327, 10 p. : ill
<https://doi.org/10.1016/j.oceaneng.2023.115327> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Inverse-model intelligent control of fin-actuated underwater robots based on drag force propulsion

Remmas, Mohamed Walid; Chemori, Ahmed; **Kruusmaa, Maarja** Ocean Engineering 2021 / art. 109883, 19 p. : ill
<https://doi.org/10.1016/j.oceaneng.2021.109883> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)