

Feedback linearization of possibly non-smooth systems

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Global linearization approach to nonlinear control systems : a brief tutorial overview

Belikov, Juri; Kaldmäe, Arvo; Kotta, Ülle Proceedings of the Estonian Academy of Sciences 2017 / p. 243-263 <https://doi.org/10.3176/proc.2017.3.01> http://www.ester.ee/record=b2355998*est https://artiklid.elnet.ee/record=b2824300*est [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Tracking control of nonlinear pneumatic actuator systems using static state feedback linearization of the input-output map

Wang, Jihong; **Kotta, Ülle;** Ke, Jia Proceedings of the Estonian Academy of Sciences. Physics. Mathematics 2007 / 1, p. 47-66 : ill