

Collaborative work between human and industrial robot in manufacturing by advanced safety monitoring system

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Model-based testing of autonomous robots using TestIt

Kanter, Gert; Vain, Jüri Journal of reliable intelligent environments 2020 / p. 15-30 <https://doi.org/10.1007/s40860-019-00095-w> [Journal metrics at Scopus](#) [Article at Scopus](#)

Test scenario generator learning for model-based testing of mobile robots

Kanter, Gert; Liibert, Marti Ingmar System assurances : modeling and management 2022 / p. 67-84 <https://doi.org/10.1016/B978-0-323-90240-3.00005-9>

TestIt: an open-source scalable long-term autonomy testing toolkit for ROS

Kanter, Gert; Vain, Jüri Conference Proceedings of 2019 10th International Conference on Dependable Systems, Services and Technologies DESSERT'2019, United Kingdom, Leeds, June 5-7, 2019 2019 / art. 8770011, p. 45-50 <http://dx.doi.org/10.1109/DESSERT.2019.8770011>