

Amfiibrobotid aitavad aimu saada veealusest elust

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Development and experimental assessment of a flexible robot fin

Gkliva, Roza; Sfakiotakis, Michael; Kruusmaa, Maarja 2018 IEEE International Conference on Soft Robotics (RoboSoft) : proceedings 2018 / p. 208-213 : ill <https://doi.org/10.1109/ROBOSOFT.2018.8404921>

Dynamic modelling of a screw actuator for improved locomotion control on various terrains

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A flapped paddle-fin for improving underwater propulsive efficiency of oscillatory actuation

Simha, Ashutosh; Gkliva, Roza; Kotta, Ülle; Kruusmaa, Maarja IEEE robotics and automation letters 2020 / p. 3176-3181 <https://doi.org/10.1109/LRA.2020.2975747> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Monitoring of coastal waves and velocities with a robotic platform

Piho, Laura; Egerer, Margit; Gkliva, Roza; Kruusmaa, Maarja; Ristolainen, Asko OCEANS 2024 - Halifax : proceedings 2024 / 5 p <https://doi.org/10.1109/OCEANS55160.2024.10754335>

A multi-terrain robot prototype with archimedean screw actuators : design, realization, modeling, and control

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Novel mechanisms of robot locomotion : variable stiffness actuators for underwater and multi-phase environments =

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Research: Robots assist in gaining glimpse of life underwater

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ROBOMINERS resilient reflectance/fluorescence spectrometers

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Salmon behavioural response to robots in an aquaculture sea cage

Kruusmaa, Maarja; Gkliva, Roza; Tuhtan, Jeffrey Andrew; Tuvikene, A.; Alfredsen, J.A. Royal Society open science 2020 / art. 191220, 14 p. : ill <https://doi.org/10.1098/rsos.191220> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Soft fluidic actuator for locomotion in multi-phase environments

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