

Optimisation of decision-making process in industrial robot selection

Kangru, Tavo; Riives, Jüri; Otto, Tauno; Kuts, Vladimir; Moor, Madis Journal of the machine engineering 2020 / p. 70–81

<https://doi.org/10.36897/jme/117788> [Journal metrics at scopus](#) [Article at Scopus](#)

Positioning error correction of autonomously movable robot arm

Vaher, Kristo; Otto, Tauno; Riives, Jüri Journal of the machine engineering 2020 / p. 152-160 : ill <https://doi.org/10.36897/jme/129013>

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