

Fault-tolerant control allocation for a bio-inspired underactuated AUV in the presence of actuator failures : design and experiments

Remmas, Mohamed Walid; Chemori, Ahmed; **Kruusmaa, Maarja** Ocean engineering 2023 / art. 115327, 10 p. : ill

<https://doi.org/10.1016/j.oceaneng.2023.115327> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Inverse-model intelligent control of fin-actuated underwater robots based on drag force propulsion

Remmas, Mohamed Walid; Chemori, Ahmed; **Kruusmaa, Maarja** Ocean Engineering 2021 / art. 109883, 19 p. : ill

<https://doi.org/10.1016/j.oceaneng.2021.109883> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)