

Consumer engagement with self-driving cars : a theory of planned behavior-informed perspective

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A model-based control of self-driving car trajectory for lanes change maneuver in a smart city

Astrov, Igor WSEAS transactions on systems and control 2023 / art. 36, p. 346-353 : ill <https://doi.org/10.37394/23203.2023.18.36> [Journal metrics at Scopus](#) [Article at Scopus](#)

A model-based LQR control of an obstacle avoidance maneuver of a self-driving car

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