

A note on the relationship between single- and multi-experiment observability for discrete-time nonlinear control systems
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Analyzing the dynamics and stability of DQ0 systems based on a Port-Hamiltonian approach

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Challenges and perspectives in control of ionic polymer-metal composite (IPMC) actuators : a survey

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Experimental validation of the Newton observer for a nonlinear flux-controlled AMB system operated with zero-bias flux

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