

Adaptive industrial robots using machine vision

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Application of Mindlin Theory to Describe the Scattering of Guided Waves From Notches in a Plate

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Collision consequence assessment of ROPAX vessels operating in the Baltic Sea

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Deposition of fine solid particles in laminar flat-plate boundary layers [Electronic resource]

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Digital Twin : concept of hybrid programming for industrial robots - use case

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Digital twin simulations based reinforcement learning for navigation and control of a wheel-on-leg mobile robot

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Multitier digital twin approach for agile supply chain management

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Novel digital twin concept for industrial application. Study case: propulsion drive system

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