

Design principle of a biomimetic underwater robot U-CAT

Salumäe, Taavi; Raag, Rasmus; Rebane, Jaan; Ernits, Andres; Toming, Gert; Ratas, Mart; Kruusmaa, Maarja OCEANS'14 MTS/IEEE St. John's : St. Johns, Newfoundland, Canada, 14-19 September 2014 2014 / [5] p. : ill

Myometry-driven compliant-body design for underwater propulsion

Akanyeti, Otar; **Listak, Madis; Ernits, Andres; Fiazza, Maria-Camilla; Toming, Gert; Kulikovskis, Guntis; Raag, Rasmus; Salumäe, Taavi; Fiorini, Paolo; Kruusmaa, Maarja** IEEE International Conference on Robotics and Automation : ICRA 2010 : Anchorage, Alaska, USA, 3-7 May 2010 2010 / p. 84-89 <https://ieeexplore.ieee.org/document/5509431>

Swimming speed control and on-board flow sensing of an artificial trout

Kruusmaa, Maarja; Toming, Gert; Salumäe, Taavi; Ježov, Jaas; Ernits, Andres 2011 IEEE International Conference on Robotics and Automation : ICRA : May 9-13, 2011, Shanghai, China 2011 / p. 1791-1796 : ill
https://www.researchgate.net/publication/224252443_Swimming_speed_control_and_on-board_flow_sensing_of_an_artificial_trout