

A bio-inspired compliant robotic fish : design and experiments

EL Daou, Hadi; Salumäe, Taavi; Toming, Gert; Kruusmaa, Maarja 2012 IEEE International Conference on Robotics and Automation : ICRA : Saint Paul, Minnesota, USA, May 14-18, 2012 2012 / p. 5340-5345 : ill
https://www.researchgate.net/publication/254041437_A_bio-inspired_compliant_robotic_fish_Design_and_experiments

A bio-mimetic design and control of a fish-like robot using compliant structures

EL Daou, Hadi; Salumäe, Taavi; Ristolainen, Asko; Toming, Gert; Listak, Madis; Kruusmaa, Maarja The 15th International Conference on Advanced Robotics : Tallinn, Estonia, June 20-23, 2011 2011 / p. 563-568 : ill

FILOSE for svenning : a flow sensing bioinspired robot

EL Daou, Hadi; Ježov, Jaas; Jung, David S.; Kruusmaa, Maarja; Listak, Madis; Salumäe, Taavi; Toming, Gert IEEE robotics and automation magazine 2014 / p. 51-62 : ill <https://doi.org/10.1109/MRA.2014.2322287> [Journal metrics at Scopus](#) [Article at Scopus](#)
[Journal metrics at WOS](#) [Article at WOS](#)

Modelling of a biologically inspired robotic fish driven by compliant parts

EL Daou, Hadi; Salumäe, Taavi; Chambers, Lily D.; McGill, William M.; Kruusmaa, Maarja Bioinspiration & biomimetics 2014 / p. 1-11 : ill <https://doi.org/10.1088/1748-3182/9/1/016010> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)