

Calculation of the traction effort of ISEAUTO self-driving vehicle

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Design of regenerative anti-lock braking system controller for 4 in-wheel-motor drive electric vehicle with road surface estimation

Aksjonov, Andrei; **Vodovozov, Valery**; Augsburg, Klaus; **Petlenkov, Eduard** International journal of automotive technology 2018 / p. 727-742 : ill <https://doi.org/10.1007/s12239-018-0070-8> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Dynamic motion energy efficiency measurement of ground vehicles

Väljaots, Eero; Sell, Raivo Proceedings of the 8th International Conference of DAAAM Baltic Industrial Engineering, 19-21st April 2012, Tallinn, Estonia. 1 2012 / p. 367-372 : ill

Hyperspectral imaging for vehicle traction effort prediction: ISEAUTO case study

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