

Fixed order stabilizing controller design via random reflection segments

Nurges, Ülo; Avanessov, Sergei The 12th International Conference on Control, Automation, Robotics and Vision, ICARCV 2012 : 5-7 December, 2012, Guangzhou, China : [proceedings] 2012 / p. 530-535 : ill
<https://ieeexplore.ieee.org/document/5983069/similar#similar>